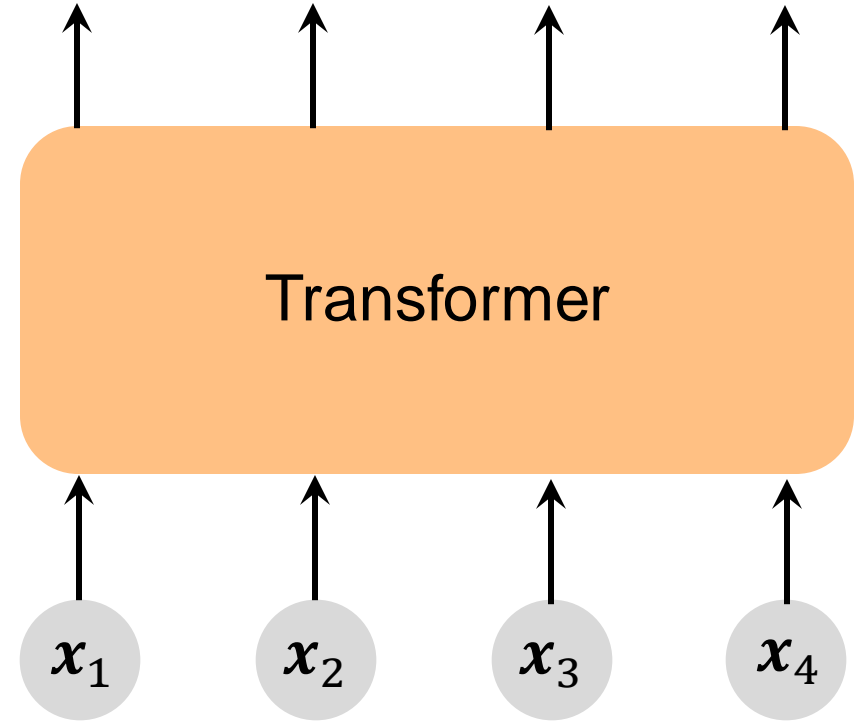
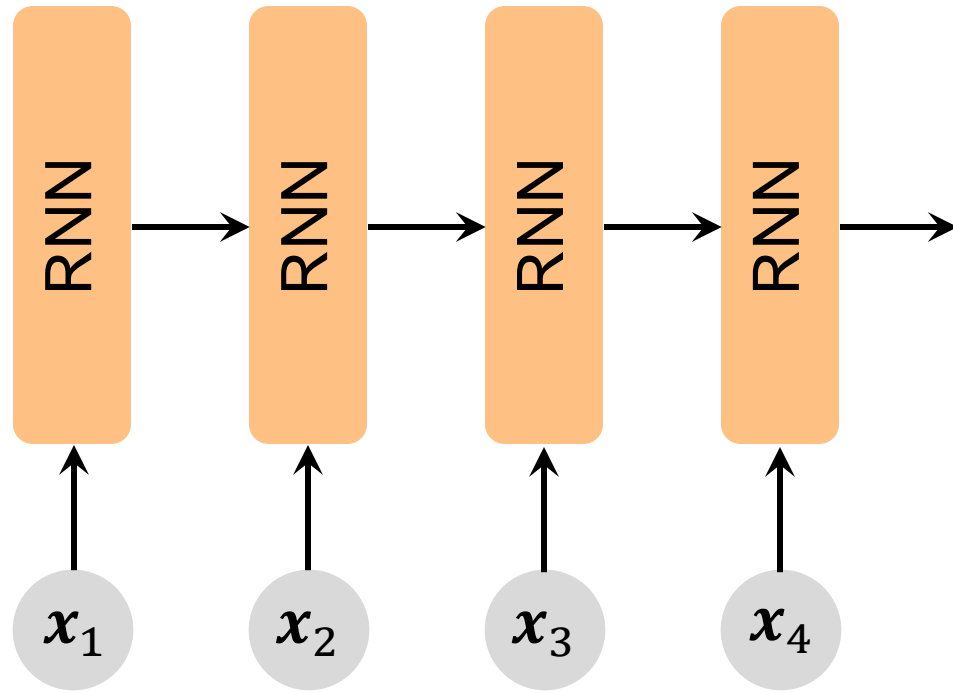
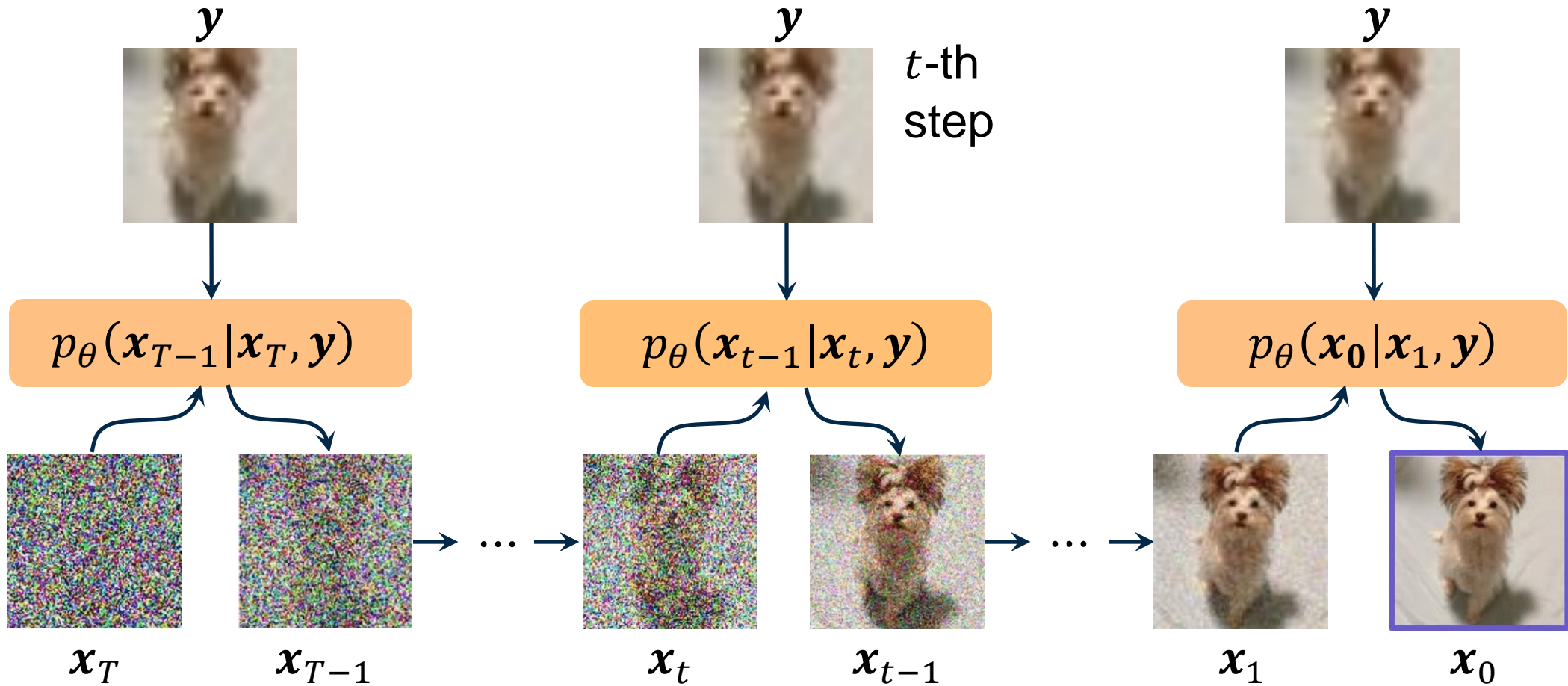


# Diffusion Restoration Models: Sequential Sampling vs Parallel Sampling

# RNN vs Transformer

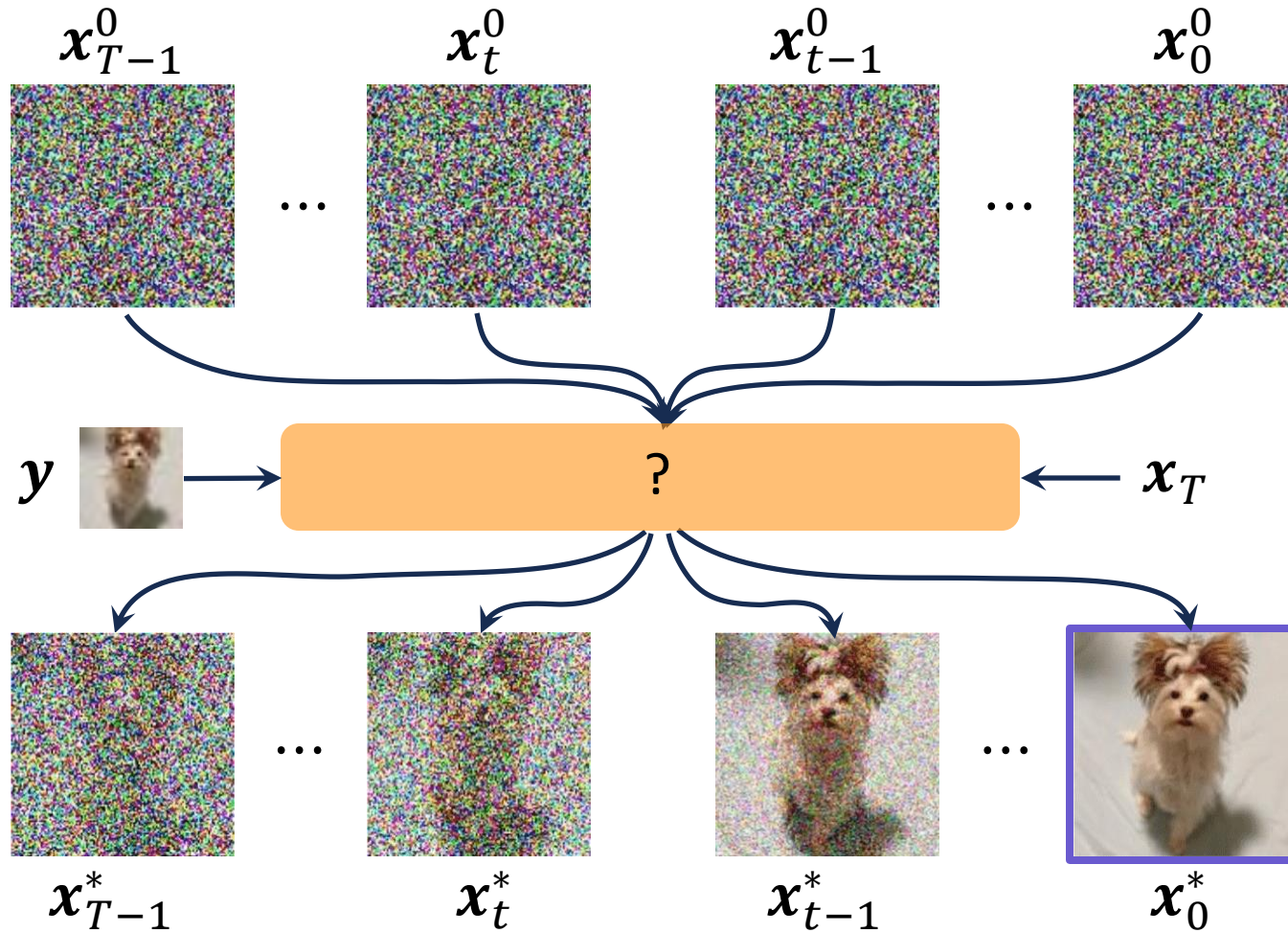


# Most Existing Diffusion Model-based IR



- Long sequential sampling has expensive sampling time and high computation costs
- Hinder understanding the relationship between the restoration results and the inputs

# Diffusion with Parallel Sampling



# Background: Diffusion Restoration

**Forward process:**

$$q(\mathbf{x}_t|\mathbf{x}_0) = \mathcal{N}(\mathbf{x}_t; \sqrt{\bar{\alpha}_t}\mathbf{x}_0, (1 - \bar{\alpha}_t)\mathbf{I}),$$

**Reverse process:**

$$q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0) = \mathcal{N}(\mathbf{x}_{t-1}; \tilde{\boldsymbol{\mu}}_t(\mathbf{x}_t, \mathbf{x}_0), \tilde{\sigma}_t^2\mathbf{I})$$

$$\tilde{\boldsymbol{\mu}}_t(\mathbf{x}_t, \mathbf{x}_0) := \frac{\sqrt{\bar{\alpha}_{t-1}}\beta_t}{1-\bar{\alpha}_t}\mathbf{x}_0 + \frac{\sqrt{\alpha_t}(1-\bar{\alpha}_{t-1})}{1-\bar{\alpha}_t}\mathbf{x}_t$$

$$\hat{\mathbf{x}}_{0|t} = \mathbf{A}^\dagger \mathbf{y} + (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A})\mathbf{x}_{0|t}$$

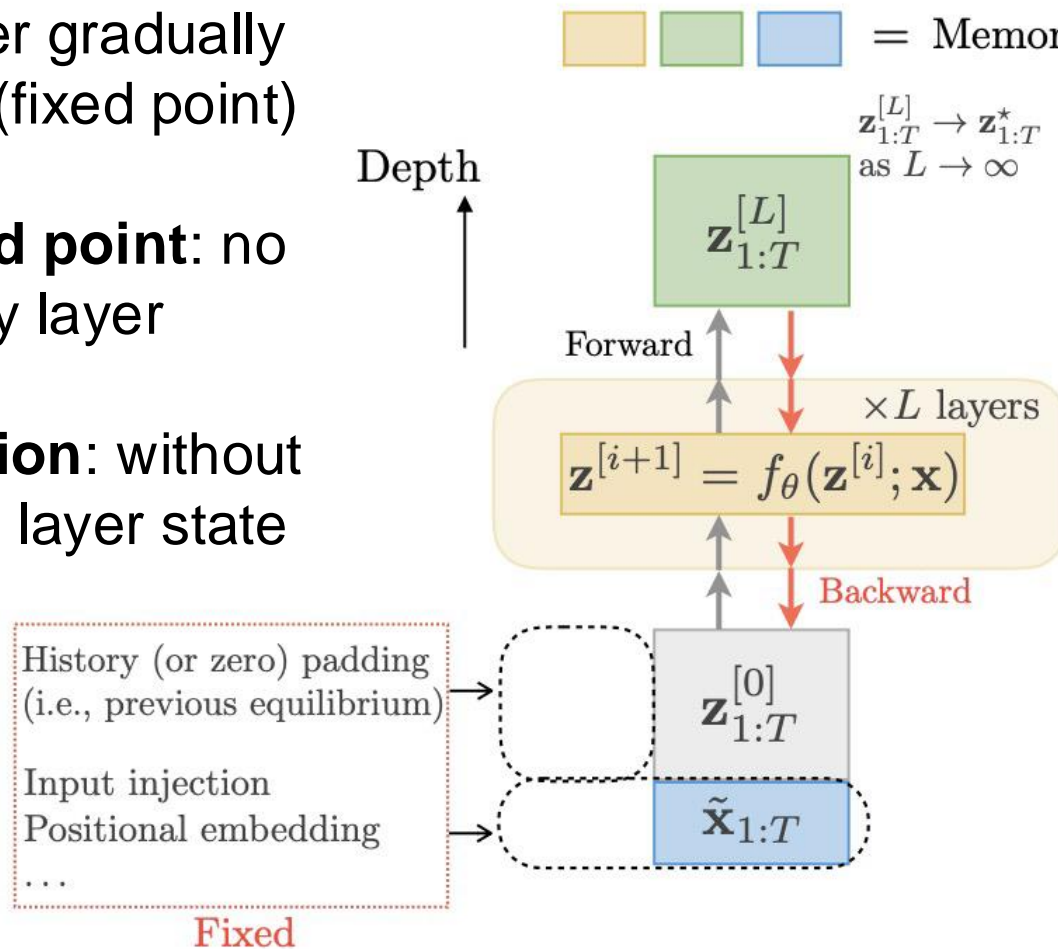
$$\mathbf{x}_{0|t} = \frac{1}{\sqrt{\bar{\alpha}_t}}(\mathbf{x}_t - \sqrt{1 - \bar{\alpha}_t}\boldsymbol{\epsilon}_\theta(\mathbf{x}_t, t))$$

# Background: Deep Equilibrium Models

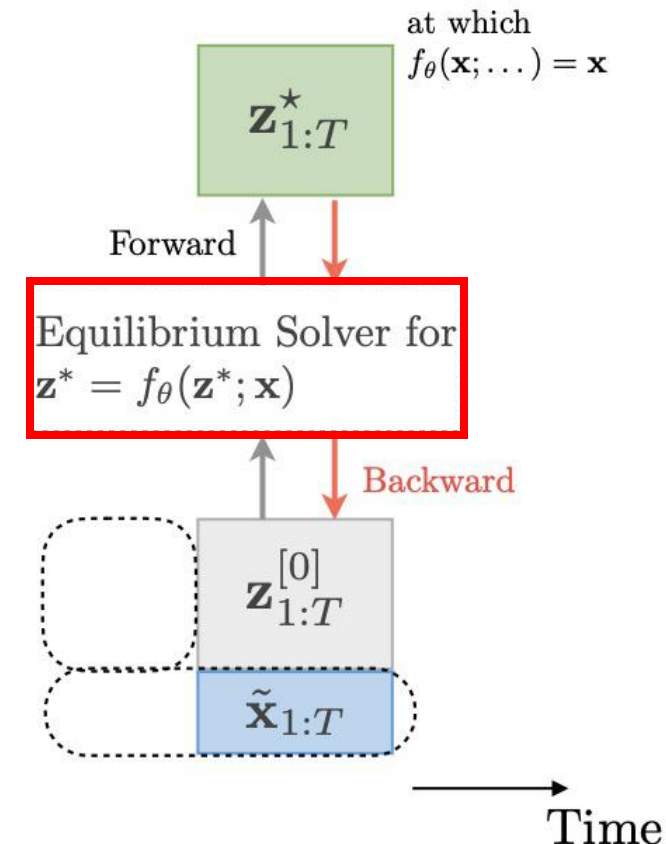
**Assumption:** each layer gradually tends to a stable value (fixed point)

**Directly solve the fixed point:** no longer calculate layer by layer

**Implicit backpropagation:** without storing the intermediate layer state



Typical Deep Neural Network



Deep Equilibrium Model

# Deep Equilibrium Modeling

$$\mathbf{x}_{0:T-1} = F(\mathbf{x}_{0:T-1}; (\mathbf{x}_T, \mathbf{y}))$$

 $\Downarrow$ 
 $\Downarrow$ 

$$\begin{bmatrix} \mathbf{x}_{T-1} \\ \mathbf{x}_{T-2} \\ \vdots \\ \mathbf{x}_{T-k} \\ \vdots \\ \mathbf{x}_0 \end{bmatrix} = \begin{bmatrix} f(\mathbf{x}_T; \mathbf{y}) \\ f(\mathbf{x}_{T-1:T}; \mathbf{y}) \\ \vdots \\ f(\mathbf{x}_{T-k+1:T}; \mathbf{y}) \\ \vdots \\ f(\mathbf{x}_{1:T}; \mathbf{y}) \end{bmatrix} \Rightarrow$$

**Closed-form solution:**

$$\mathbf{x}_{T-k} = \frac{\sqrt{\bar{\alpha}_{T-k}}}{\sqrt{\bar{\alpha}_T}} (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A}) \mathbf{x}_T + \mathbf{A}^\dagger \mathbf{A} \mathbf{z}_{T-k+1} + \sum_{s=T-k}^{T-1} \frac{\sqrt{\bar{\alpha}_{T-k}}}{\sqrt{\bar{\alpha}_s}} (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A}) \mathbf{z}_{s+1}$$

**Anderson acceleration solver:**

$$\mathbf{x}_{0:T-1}^* = \text{RootSolve}(F(\mathbf{x}_{0:T-1}; (\mathbf{x}_T, \mathbf{y})) - \mathbf{x}_{0:T-1})$$

# Initialization Optimization via DEQ Inversion

## DEQ Inversion:

Loss function:  $\mathcal{L} = \ell(\phi(\mathbf{x}_0^*); \varphi(\mathbf{y}))$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{x}_T} = - \frac{\partial \mathcal{L}}{\partial \mathbf{x}_{0:T}^*} \underbrace{\left( J_g^{-1} \Big|_{\mathbf{x}_{0:T}^*} \right)}_{\text{inverse Jacobian}} \frac{\partial F(\mathbf{x}_{0:T-1}^*; (\mathbf{x}_T, \mathbf{y}))}{\partial \mathbf{x}_T}$$

**Gradient descent:**  $\mathbf{x}_T \leftarrow \mathbf{x}_T + \lambda \cdot \partial \mathcal{L} / \partial \mathbf{x}_T$



# A New Zero-shot Diffusion Restoration

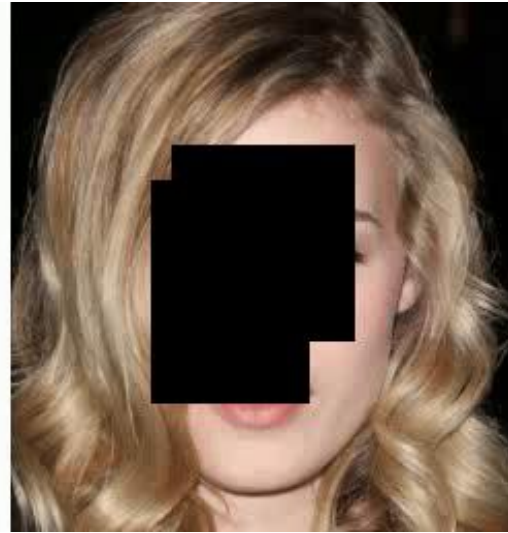
Super-Rresolution



Deblurring



Inpainting



Colorization



# Quantitative Comparisons

Super-resolution

Datasets	Methods	2×SR			4×SR		
		PSNR↑	SSIM↑	LPIPS↓	PSNR↑	SSIM↑	LPIPS↓
ImageNet	Baseline	29.63	0.875	0.165	25.15	0.699	0.351
	DGP [55]	22.32	0.583	0.426	18.35	0.398	0.529
	DPS [20]	22.40	0.597	0.405	20.34	0.488	0.464
	ILVR [19]	23.36	0.613	0.334	22.76	0.583	0.383
	DiffPIR [87]	27.16	0.790	0.214	24.31	0.649	0.350
	DDRM [41]	31.43	0.906	0.117	26.21	0.745	0.288
	DDNM [68]	31.81	0.908	0.097	26.49	0.753	0.266
	<b>DeqIR (Ours)</b>	<b>32.35</b>	<b>0.913</b>	<b>0.082</b>	<b>27.47</b>	<b>0.781</b>	<b>0.230</b>
CelebA-HQ	Baseline	35.87	0.953	0.099	30.12	0.857	0.240
	DGP [55]	28.61	0.809	0.279	25.25	0.690	0.405
	DPS [20]	28.71	0.818	0.219	25.01	0.710	0.282
	ILVR [19]	27.31	0.783	0.234	27.09	0.775	0.245
	DiffPIR [87]	32.51	0.882	0.156	28.60	0.795	0.228
	DDRM [41]	<b>36.76</b>	0.953	0.074	31.91	0.880	0.149
	DDNM [68]	36.37	0.950	0.065	31.86	0.876	<b>0.136</b>
	<b>DeqIR (Ours)</b>	36.63	<b>0.954</b>	<b>0.062</b>	<b>32.22</b>	<b>0.889</b>	0.155

Deblurring

Deblur (Gaussian)			Deblur (anisotropic)			NFEs /Iters
PSNR↑	SSIM↑	LPIPS↓	PSNR↑	SSIM↑	LPIPS↓	
18.22	0.529	0.433	20.86	0.544	0.480	-
21.81	0.522	0.472	20.77	0.459	0.504	1500
22.04	0.569	0.394	21.82	0.561	0.381	1000
-	-	-	-	-	-	100
25.32	0.673	0.296	23.37	0.535	0.439	100
40.70	0.978	0.040	37.69	0.964	0.057	20
<b>43.83</b>	<b>0.989</b>	<b>0.018</b>	38.40	0.970	0.038	100
43.42	0.987	0.021	<b>39.47</b>	<b>0.973</b>	<b>0.036</b>	15
18.94	0.704	0.337	23.16	0.727	0.354	-
27.02	0.738	0.372	25.73	0.663	0.426	1500
27.56	0.775	0.229	26.91	0.754	0.234	1000
-	-	-	-	-	-	100
30.63	0.835	0.197	29.32	0.802	0.232	100
43.06	0.983	0.036	41.27	0.976	0.053	20
46.99	0.991	0.021	43.43	0.983	0.037	100
<b>47.18</b>	<b>0.992</b>	<b>0.019</b>	<b>43.57</b>	<b>0.984</b>	<b>0.036</b>	15

Inpainting

Methods	Text mask			Stripe mask		
	PSNR↑	SSIM↑	LPIPS↓	PSNR↑	SSIM↑	LPIPS↓
Baseline	14.55	0.642	0.515	9.02	0.131	0.730
Palette [59]	38.09	0.978	0.027	25.91	0.733	0.343
DDRM [41]	37.25	0.969	0.223	34.34	0.933	0.223
RePaint [53]	38.54	0.974	0.039	36.25	0.951	0.086
DDNM [68]	39.45	0.980	<b>0.023</b>	36.75	<b>0.957</b>	<b>0.076</b>
<b>DeqIR (Ours)</b>	<b>39.72</b>	<b>0.981</b>	0.026	<b>36.99</b>	0.948	0.091

Colorization

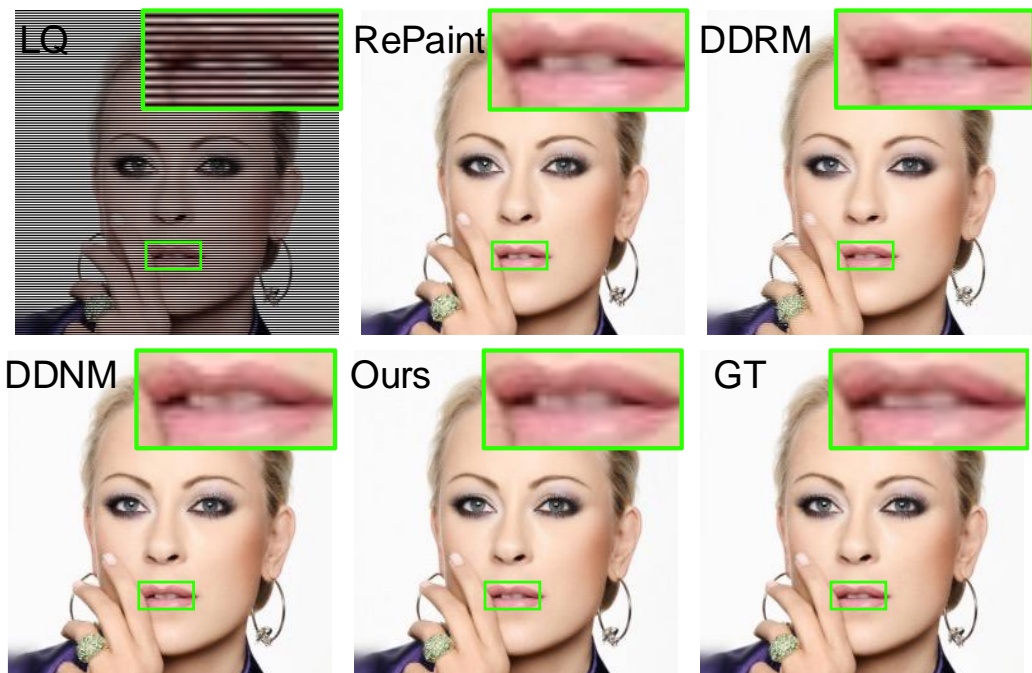
Methods	ImageNet			CelebA-HQ		
	Cons↓	LPIPS↓	FID↓	Cons↓	LPIPS↓	FID↓
Baseline	0	0.196	90.93	0	0.210	70.69
DGP [55]	-	0.256	99.86	-	0.218	73.24
DDRM [41]	265.08	0.223	79.42	472.25	0.245	57.29
DDNM [68]	45.07	0.186	77.21	51.43	0.139	45.73
<b>DeqIR (Ours)</b>	<b>43.15</b>	<b>0.171</b>	<b>70.94</b>	<b>50.16</b>	<b>0.092</b>	<b>43.98</b>

# Qualitative Comparisons

Super-resolution



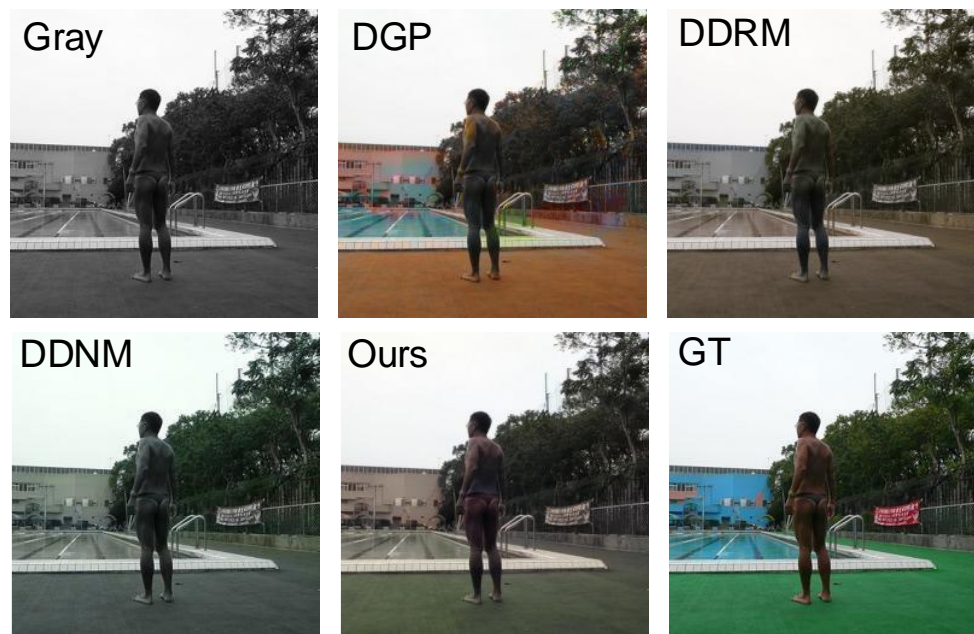
Inpainting



Deblurring



Colorization

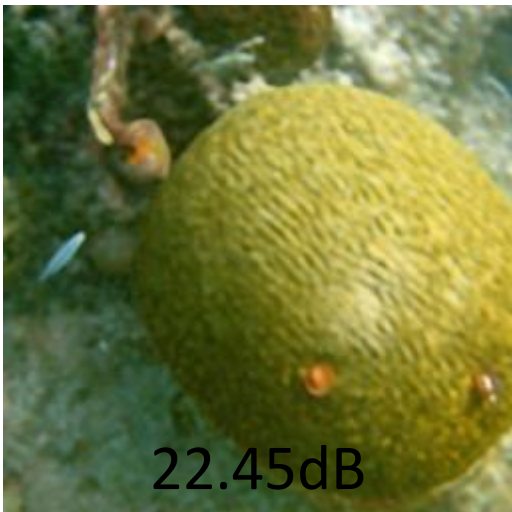


# Interesting Applications of DEQ Inversion

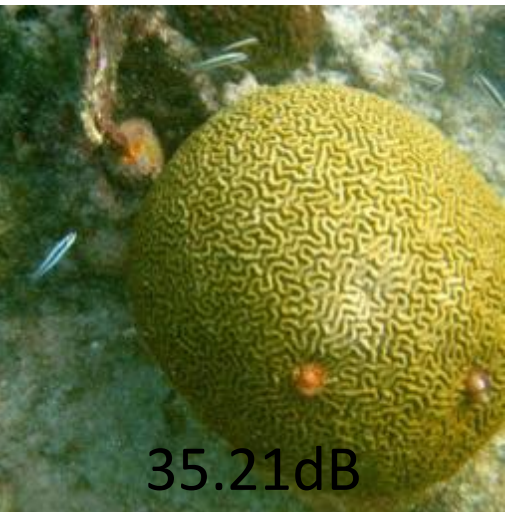
LR input



w/o inversion



w/ inversion



GT



gray input



reference



w/o inversion



w/ inversion



# PSNR Improvement with DEQ Inversion

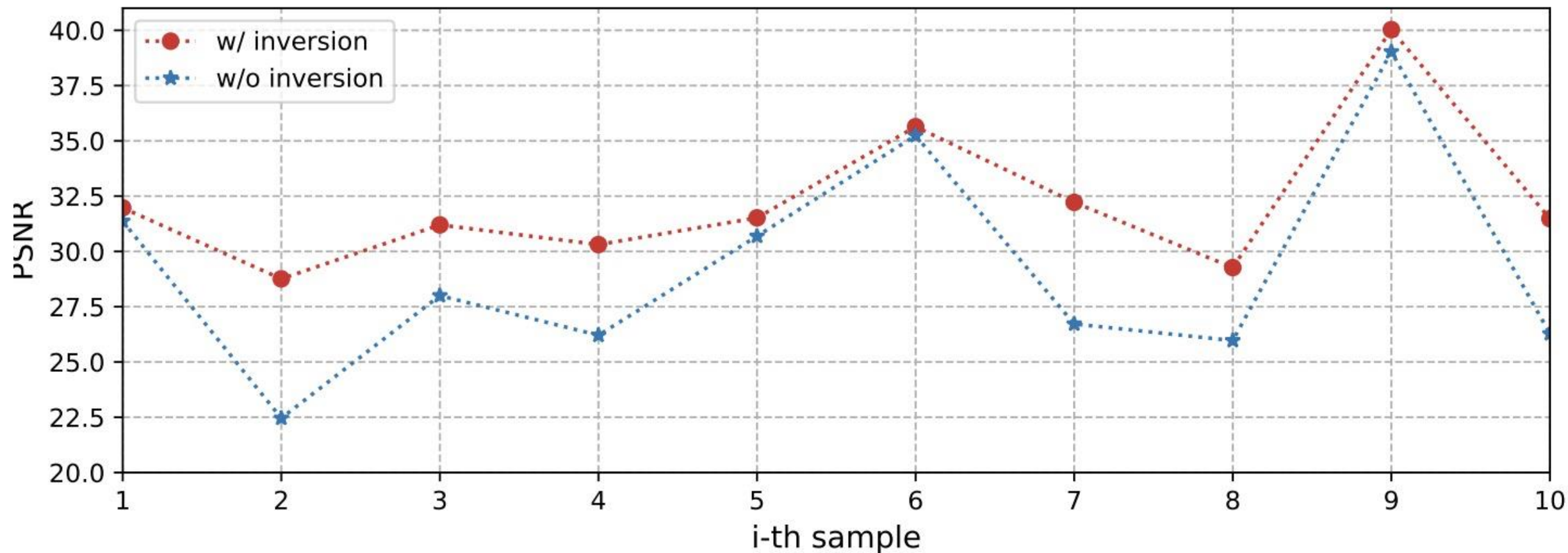
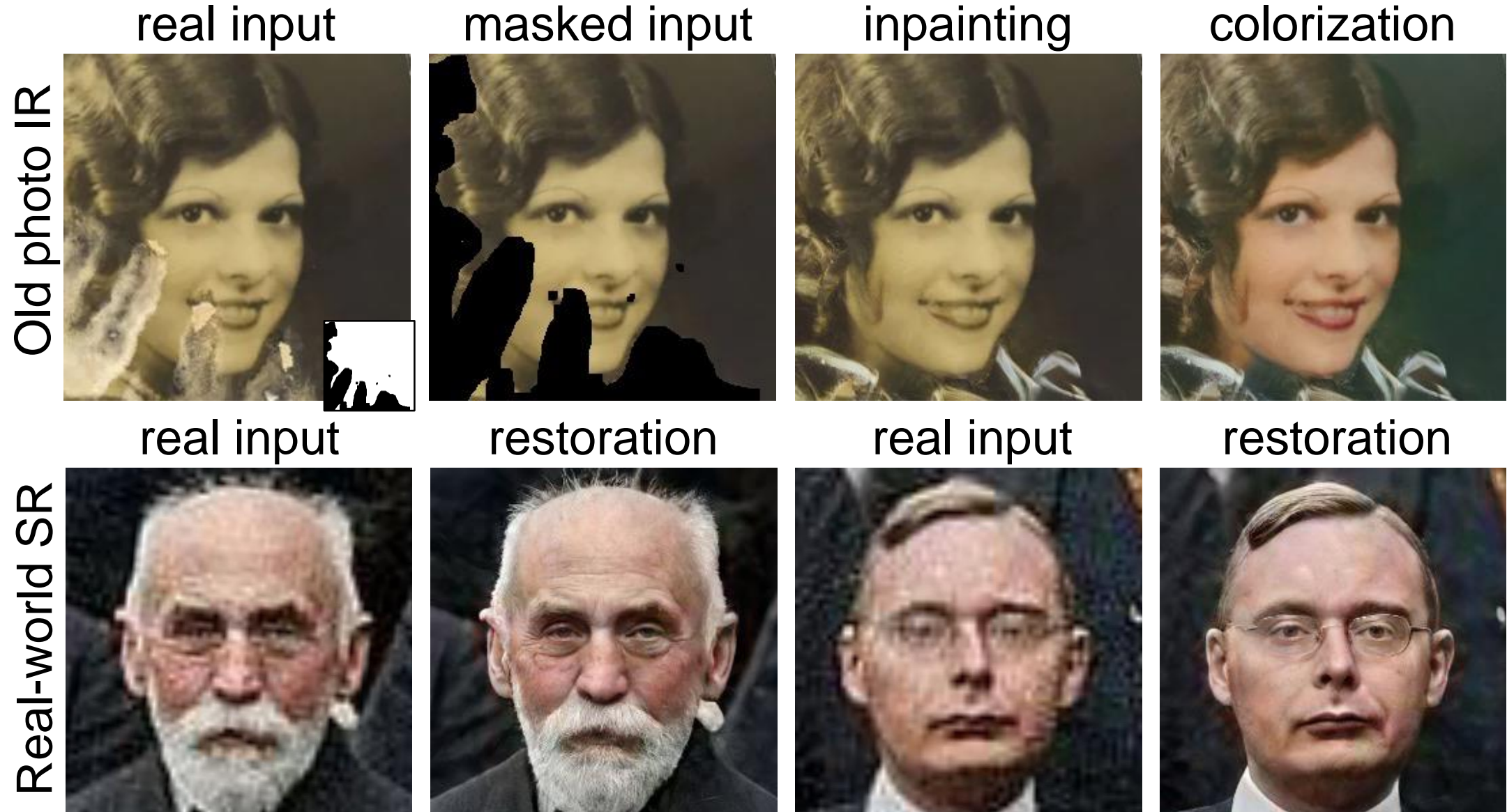


Figure D20. PSNR improvement of using initialization optimization on ImageNet (we show the first 10 samples).

# Real-World Applications



# Ablation Study

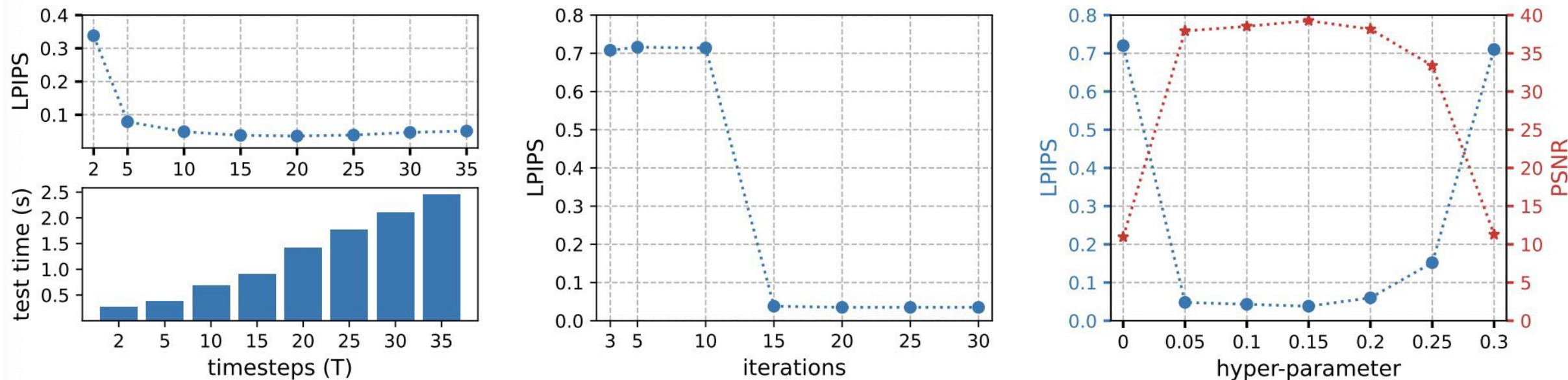
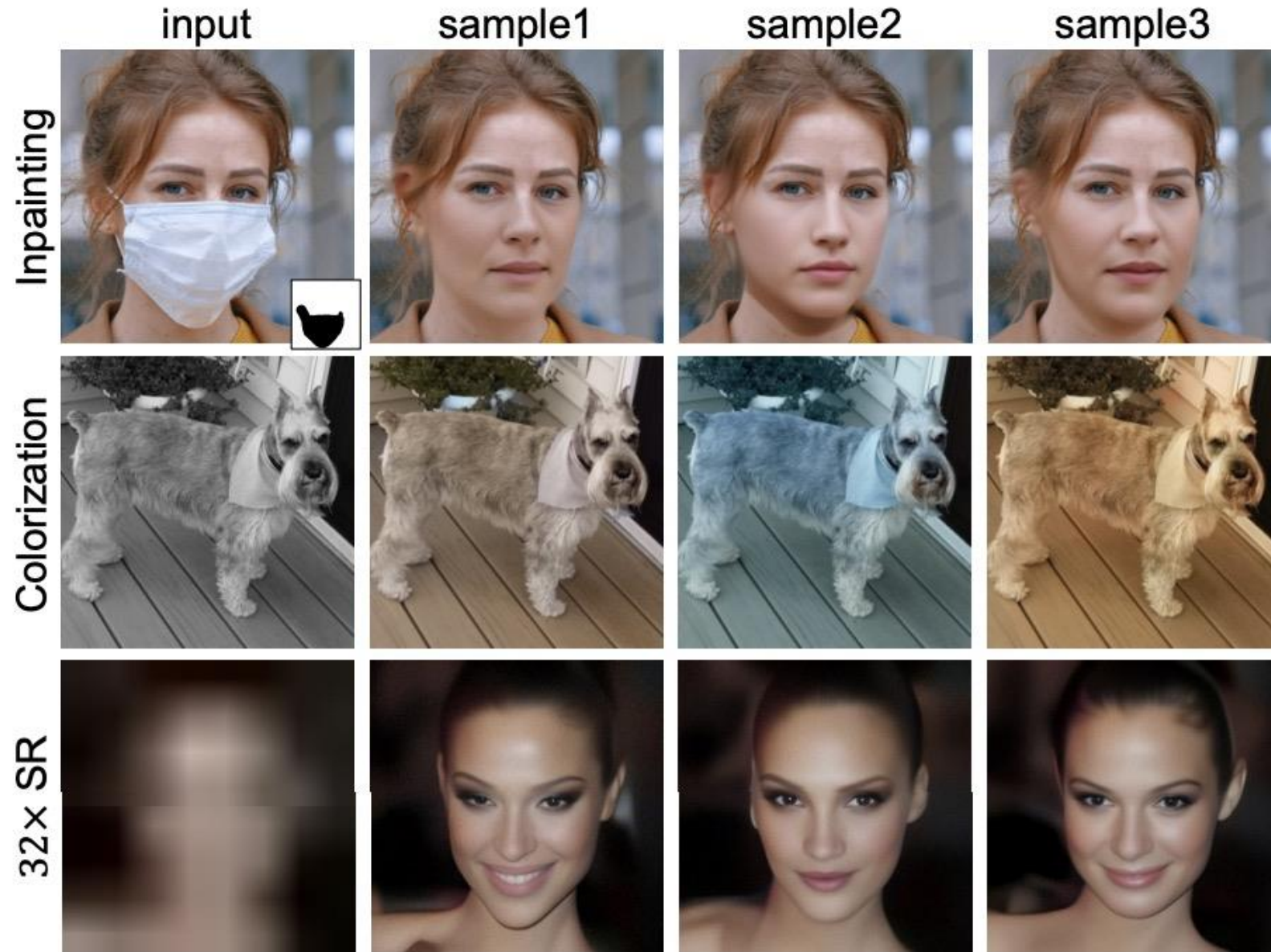


Figure 8. Ablation study of timesteps (left), iteration (middle) and hyper-parameters (right) for anisotropic deblurring on ImageNet.

# Diversity of Restoration





Thanks for your attention!