

# Learning Architectures and Loss Functions in Continuous Space

Fei Tian

Machine Learning Group

Microsoft Research Asia



#### Self-Introduction

- Researcher @ MSRA Machine Learning Group
  - Joined in July, 2016
- Research Interests:
  - Machine Learning for NLP (especially NMT)
  - Automatic Machine Learning
- More Information: <a href="https://ustctf.github.io">https://ustctf.github.io</a>



#### Outline

Overview

- Efficiently optimizing continuous decisions
  - Loss Function Teaching

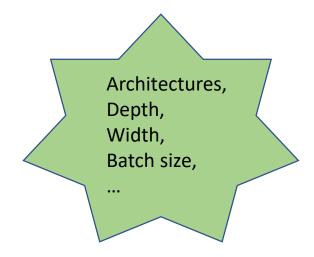
- Continuous space for discrete decisions
  - Neural Architecture Optimization



## Automatic Machine Learning

#### Automate every **decision** in machine learning







## Why Continuous Space?

- Life is easier if we have gradients
  - For example, we have a bunch of powerful gradient-based optimization algorithms

- Representation is compact
  - One of |V| representations of words **V.S.** word embeddings



## The Role of Continuous Space in AutoML

- For continuous decisions
  - How to efficiently optimize them?
    - And the more important, elegantly
- Our work:

Loss Function Teaching

- For discrete decisions
  - How to effectively cast them into continuous space?
- Our work:

Neural Architecture Optimization



# Learning to Teach with Dynamic Loss Functions

Lijun Wu, Fei Tian, Yingce Xia, Tao Qin, Tie-Yan Liu NeurIPS 2018



## Loss Function Teaching

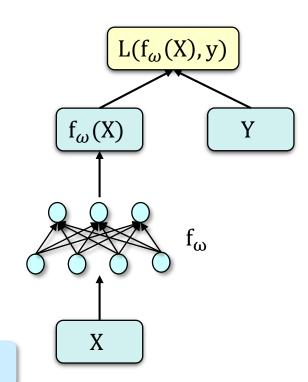
- Recap to loss function  $L(f_{\omega}(x), y)$ 
  - Typical examples:
    - Cross-Entropy:  $L = -\log p(x) \cdot \vec{y}, \ \vec{y}_i = \mathbf{1}_{i=y}$
    - Maximum Margin:  $L = \max_{y' \neq y} \log p_{y'} \log p_y$
  - Learning objective of  $f_{\omega}$ :
    - Minimize *L*

• 
$$\omega_t = \omega_{t-1} - \eta \frac{\partial L}{\partial \omega_{t-1}}$$

Objective of loss function teaching:

Discover best loss function L to train student model  $f_{\omega}$ 

• Ultimate goal: improve the performance of  $f_{\omega}$ 





## Why is it called "Teaching"?

• If we view model  $f_{\omega}$  as students, then L is the exams

- Good teachers are adaptive :
  - They set good exams according to the status of the students
- An analogy:
  - Data (x, y) is the textbook
  - Curriculum learning schedules the textbooks (data) per the status of the student model



## Can We Achieve Automatic Teaching?

The first task: design a good decision space

- Our way: use another (parametric) neural network  $L_{\phi}(f_{\omega}(x),y)$  as the loss function
  - The decision space: coefficients  $\phi$
  - It is continuous



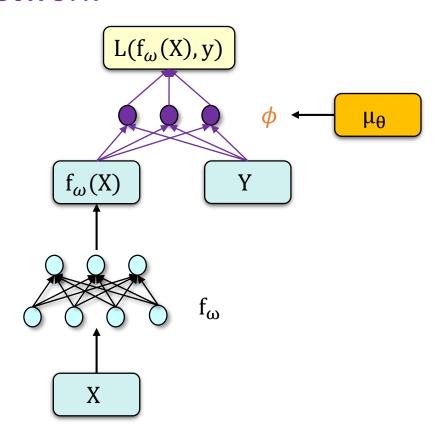
### Automatic Loss Function Teaching, cont.

- Assume the loss function itself is a neural network
  - $L_{\phi}(f_{\omega}(x), y)$ , with  $\phi$  as its coefficient
  - For example, generalized cross-entropy loss

• 
$$L_{\phi} = \sigma(-\log^T p(x) \, \mathbf{W} \vec{y} + b)$$

•  $\phi = \{W, b\}$ 

- A parametric teacher model  $\mu_{\theta}$ 
  - Output  $\phi$
  - $\phi = \mu_{\theta}$

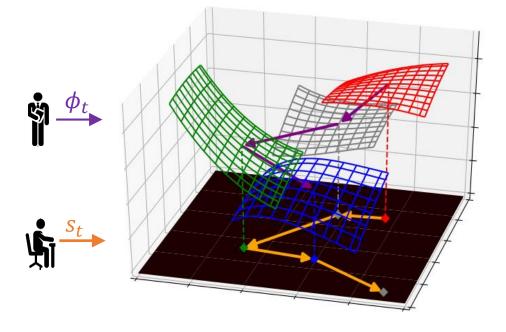




## How to Be Adaptive?

• Extract feature  $s_t$  at different training step t of student model  $f_\omega$ 

- The coefficients are adaptive
  - $\phi_t = \mu_{\theta}(s_t)$ , generating adaptive loss functions  $L_{\phi_t}(f_{\omega}(x), y)$





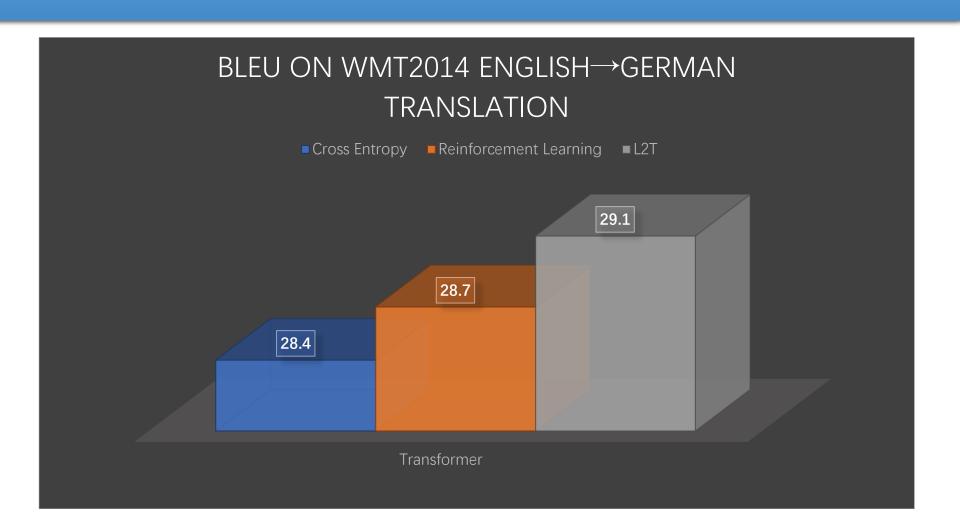
## How to Optimize the Teacher Model?

Hyper gradient

• 
$$\frac{\partial L_{dev}}{\partial \phi} = \frac{\partial L_{dev}}{\partial \omega_T} \frac{\partial \omega_T}{\partial \phi} = \frac{\partial L_{dev}}{\partial \omega_T} \left( \frac{\partial \omega_{T-t}}{\partial \phi} - \eta_{T-1} \frac{\partial^2 L_{train}(\omega_{T-1})}{\partial \omega_{T-1} \partial \phi} \right)$$

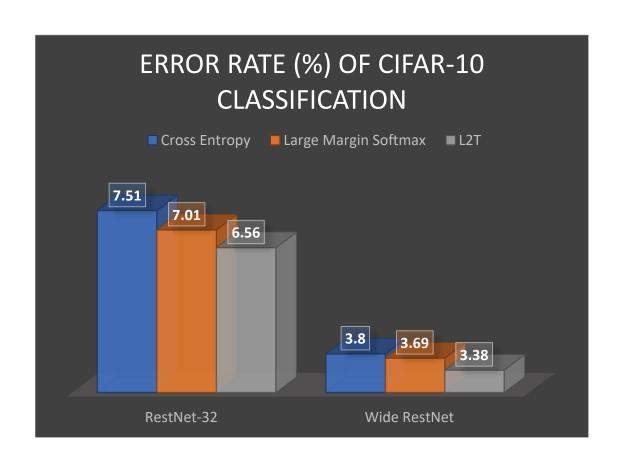


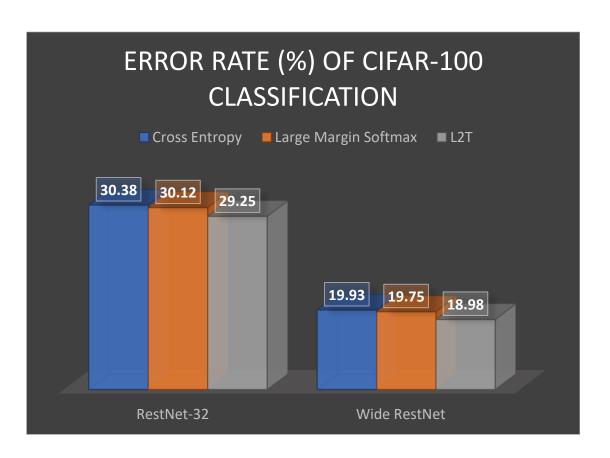
## Neural Machine Translation Experiment





### Experiments: Image Classification







#### Till now...

- We talked about how to set continuous decisions for a particular AutoML task
- And how to effectively optimize it
- But what would if the design space is **discrete**?



## Neural Architecture Optimization

Renqian Luo, Fei Tian, Tao Qin, En-Hong Chen, Tie-Yan Liu NeurIPS 2018



## The Background: Neural Architecture Search

- There might be no particular need to introduce the basis...
- Two mainstream algorithms:
  - Reinforcement Learning and Evolutionary Computing



## How to Cast the Problem into Continuous Space?

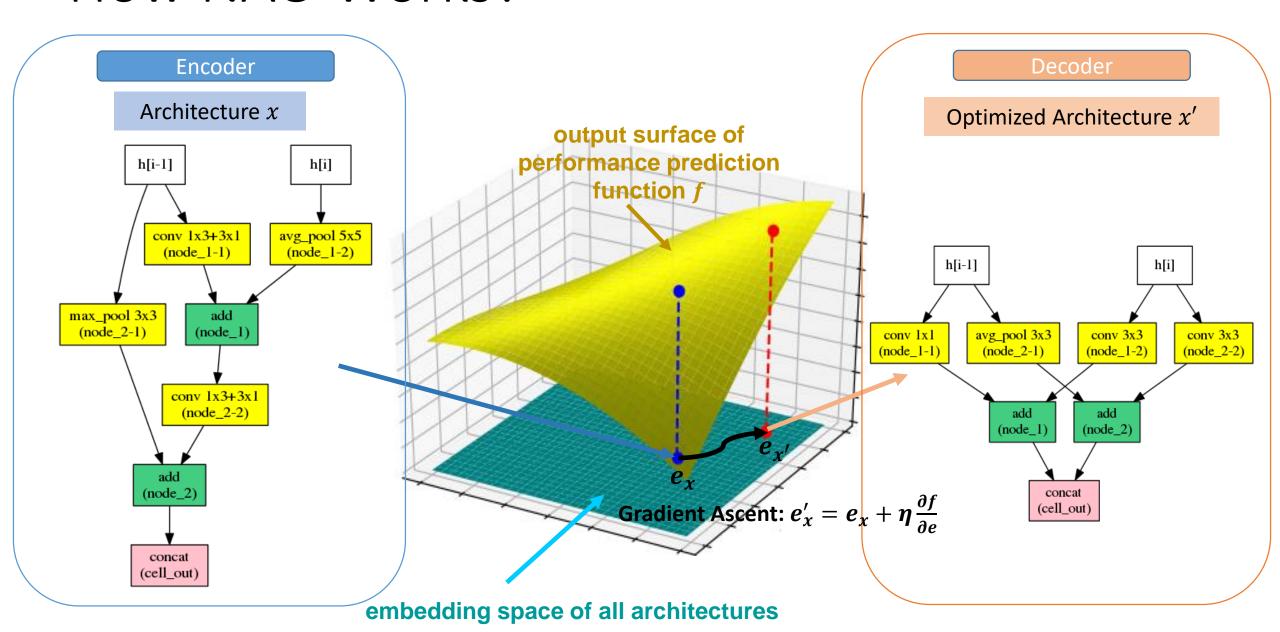
Intuitive Idea

Map the (discrete) architectures into continuous embeddings -> Optimize the embeddings -> Revert back to the architectures

- How to optimize?
  - Use the help of a performance predictor function f

#### How NAO Works?







## Why the Encoder (including perf predictor) Could Work? Two Tricks

- Normalize the performance into (0,1)
  - Sometimes even with CDF

- Data augmentation
  - $(x, y) \rightarrow (x', y)$ , if x and x' are symmetric
  - Improve the pairwise accuracy by 2% on CIFAR-10



## Why the Decoder (i.e., perfect recovery) Could Work?

- Sentence-wise AutoEncoder with attention mechanism is easy to train
  - You can even obtain near 100 BLEU on test set!
  - So sometimes need *perturbations* to avoid trivial solution (e.g., in unsupervised machine translation [1,2])
  - *f* happens to be the *perturbation*

- 1. Artetxe, Mikel, et al. "Unsupervised neural machine translation." ICLR 2018
- 2. Lample, Guillaume, et al. "Unsupervised machine translation using monolingual corpora only." ICLR 2018



## Experiments: CIFAR-10

Method	Error Rate	Resource (#GPU × #Hours)
ENAS	2.89	12
NAO-WS	2.80	7
AmoebaNet	2.13	3150 * 24
Hie-EA	3.15	300 * 24
NAO	2.10	200 * 24



## Experiments: Transfer to CIFAR-100

Model	В	N	F	#op	Error (%)
DenseNet-BC [19]	/	100	40	/	17.18
Shake-shake [15]	/	/	/	/	15.85
Shake-shake + Cutout [12]	/	/	/	/	15.20
NASNet-A [48]	5	6	32	13	19.70
NASNet-A [48] + Cutout	5	6	32	13	16.58
NASNet-A [48] + Cutout	5	6	128	13	16.03
PNAS [27]	5	3	48	8	19.53
PNAS [27] + Cutout	5	3	48	8	17.63
PNAS [27] + Cutout	5	6	128	8	16.70
ENAS [37]	5	5	36	5	19.43
ENAS [37] + Cutout	5	5	36	5	17.27
ENAS [37] + Cutout	5	5	36	5	16.44
AmoebaNet-B [38]	5	6	128	19	17.66
AmoebaNet-B [38] + Cutout	5	6	128	19	15.80
NAONet + Cutout	5	6	36	11	15.67
NAONet + Cutout	5	6	128	11	14.36



## Experiments: PTB Language Modelling

Method	Perplexity	Resource (#GPU × #Hours)
NASNet	62.4	1e4 CPU days
ENAS	58.6	12
NAO	56.0	300
NAO-WS	56.4	8



## Experiments: Transfer to WikiText2

Models and Techniques	#params	Test Perplexity
Variational LSTM + weight tying [20]	28M	87.0
LSTM + continuos cache pointer [16]	-	68.9
LSTM [33]	33	66.0
4-layer LSTM + skip connection + averaged weight drop + weight penalty + weight tying [32]	24M	65.9
LSTM + averaged weight drop + Mixture of Softmax + weight penalty + weight tying [44]	33M	63.3
ENAS + weight tying + weight penalty [37] (searched on PTB)	33M	70.4
DARTS + weight tying + weight penalty (searched on PTB)	33M	66.9
NAO + weight tying + weight penalty (searched on PTB)	36M	66.5



### Open Source

https://github.com/renqianluo/NAO



## Thanks!

We are hiring! Send me a message if you are interested: fetia@microsoft.com

#### The Panel Discussion

- AutoML具体包括什么(网络结构搜索, 超参数搜索, 传统机器学习模型等)?
- AutoML与meta-learning的关系?
- NAS的局限性?如何完全除去人为干预?
- NAS与representation/transfer learning?
- 如何看待Random Search and Reproducibility for NAS
- RL or ES or SGD, gradient-based NAS是未来吗?